

# COL7160 : Quantum Computing

## Lecture 25: Mixed States, Density Matrix, and Measurements

**Instructor:** Rajendra Kumar

**Scribe:** Abhinav Rajesh Shripad

### 1 Pure States vs. Mixed States

So far, we have worked exclusively with *pure states*: quantum states that are fully specified by a single state vector  $|\psi\rangle$  in a Hilbert space  $\mathcal{H}$ . However a system may have been prepared by a classical process that produces  $|\psi_i\rangle$  with probability  $p_i$ . In either case the state is *mixed*: a classical probability distribution over pure states.

**Definition 1** (Ensemble). An *ensemble* is a set  $\{(p_i, |\psi_i\rangle)\}$  where each  $|\psi_i\rangle$  is a (normalized) pure state and  $\{p_i\}$  is a probability distribution, i.e.  $p_i \geq 0$  for all  $i$  and  $\sum_i p_i = 1$ .

**Example 2.** A source emits  $|0\rangle$  with probability  $\frac{1}{2}$  and  $|1\rangle$  with probability  $\frac{1}{2}$ . The ensemble is

$$\left\{ \left( \frac{1}{2}, |0\rangle \right), \left( \frac{1}{2}, |1\rangle \right) \right\}.$$

This is *not* the same as the pure superposition  $|+\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$ , even though the measurement probabilities in the computational basis agree.

### 2 Density Matrix (Density Operator)

The density matrix provides a unified mathematical description of both pure and mixed states.

**Definition 3** (Density Operator). The *density operator* (or *density matrix*) associated with an ensemble  $\{(p_i, |\psi_i\rangle)\}$  is

$$\rho = \sum_i p_i |\psi_i\rangle\langle\psi_i|.$$

**Proposition 4** (Characterization of Density Operators). A linear operator  $\rho$  on  $\mathcal{H}$  is a valid density operator if and only if

1.  $\rho \succeq 0$  (positive semi-definite),
2.  $\text{tr}(\rho) = 1$  (unit trace).

*Proof.* ( $\Rightarrow$ ) For any  $|\varphi\rangle$ ,  $\langle\varphi|\rho|\varphi\rangle = \sum_i p_i |\langle\varphi|\psi_i\rangle|^2 \geq 0$ , so  $\rho \succeq 0$ . Moreover,  $\text{tr}(\rho) = \sum_i p_i \text{tr}(|\psi_i\rangle\langle\psi_i|) = \sum_i p_i \langle\psi_i|\psi_i\rangle = \sum_i p_i = 1$ .

( $\Leftarrow$ ) Any positive semi-definite, unit-trace operator has a spectral decomposition  $\rho = \sum_j \lambda_j |e_j\rangle\langle e_j|$  with  $\lambda_j \geq 0$  and  $\sum_j \lambda_j = 1$ , so  $\{(\lambda_j, |e_j\rangle)\}$  is a valid ensemble.  $\square$

### 3 Evolution of Density Operators

Suppose a closed quantum system evolves by a unitary  $U$ . If the system is in state  $|\psi_i\rangle$ , it evolves to  $U|\psi_i\rangle$ . Therefore the density operator transforms as

$$\rho \longmapsto U\rho U^\dagger.$$

This is the *unitary conjugation* rule, and it follows immediately from the linearity of the density operator construction.

**Homework.** Show that unitary conjugation preserves positive semi-definiteness and unit trace.

## 4 Measurements and the Density Operator

### Projective Measurements

Let  $\{P_m\}$  be a complete set of orthogonal projectors:

$$P_m P_{m'} = \delta_{mm'} P_m, \quad \sum_m P_m = I.$$

**Proposition 5** (Born Rule for Mixed States). *Given a system with density operator  $\rho$ , the probability of outcome  $m$  is*

$$\Pr[m] = \text{tr}(P_m \rho),$$

and the post-measurement state is

$$\rho_m = \frac{P_m \rho P_m}{\text{tr}(P_m \rho)}.$$

*Proof.* If the system is in state  $|\psi_i\rangle$  with probability  $p_i$ , then by the standard Born rule,

$$\Pr[m \mid |\psi_i\rangle] = \langle \psi_i | P_m | \psi_i \rangle = \text{tr}(P_m |\psi_i\rangle \langle \psi_i|).$$

Averaging over the ensemble,

$$\Pr[m] = \sum_i p_i \text{tr}(P_m |\psi_i\rangle \langle \psi_i|) = \text{tr}\left(P_m \sum_i p_i |\psi_i\rangle \langle \psi_i|\right) = \text{tr}(P_m \rho).$$

The post-measurement state follows from Bayes' rule applied to each branch. □

### Positive Operator-Valued Measures (POVMs)

A more general measurement is described by a *POVM*: a set of positive semi-definite operators  $\{M_m\}$  satisfying  $\sum_m M_m = I$ .

**Definition 6** (POVM). A *positive operator-valued measure* is a collection  $\{M_m\}$  with  $M_m \succeq 0$  for all  $m$  and  $\sum_m M_m = I$ .

The probability of outcome  $m$  when measuring  $\rho$  is

$$\Pr[m] = \text{tr}(M_m \rho).$$

A POVM does not specify the post-measurement state; for that one needs a *measurement model* (a set of Kraus operators  $\{K_m\}$  with  $M_m = K_m^\dagger K_m$ ).

*Remark 7.* Projective measurements are a special case of POVMs with  $M_m = P_m$  (idempotent elements).